



Basics of Signal Processing



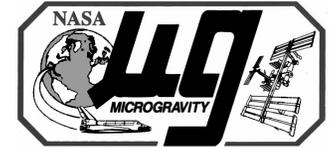
Section 7

Basics of Signal Processing

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Outline

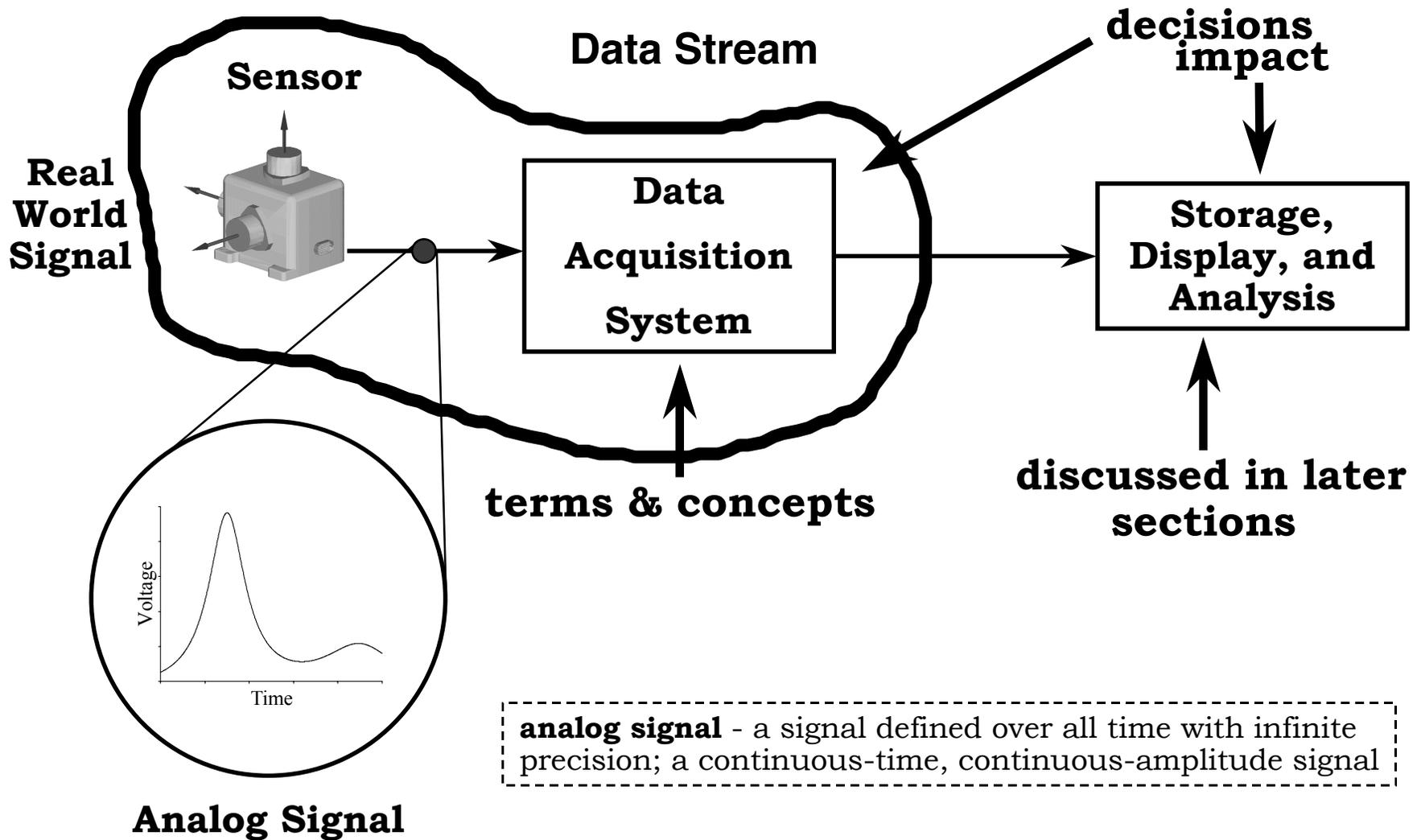
1. Block Diagram of Data Stream

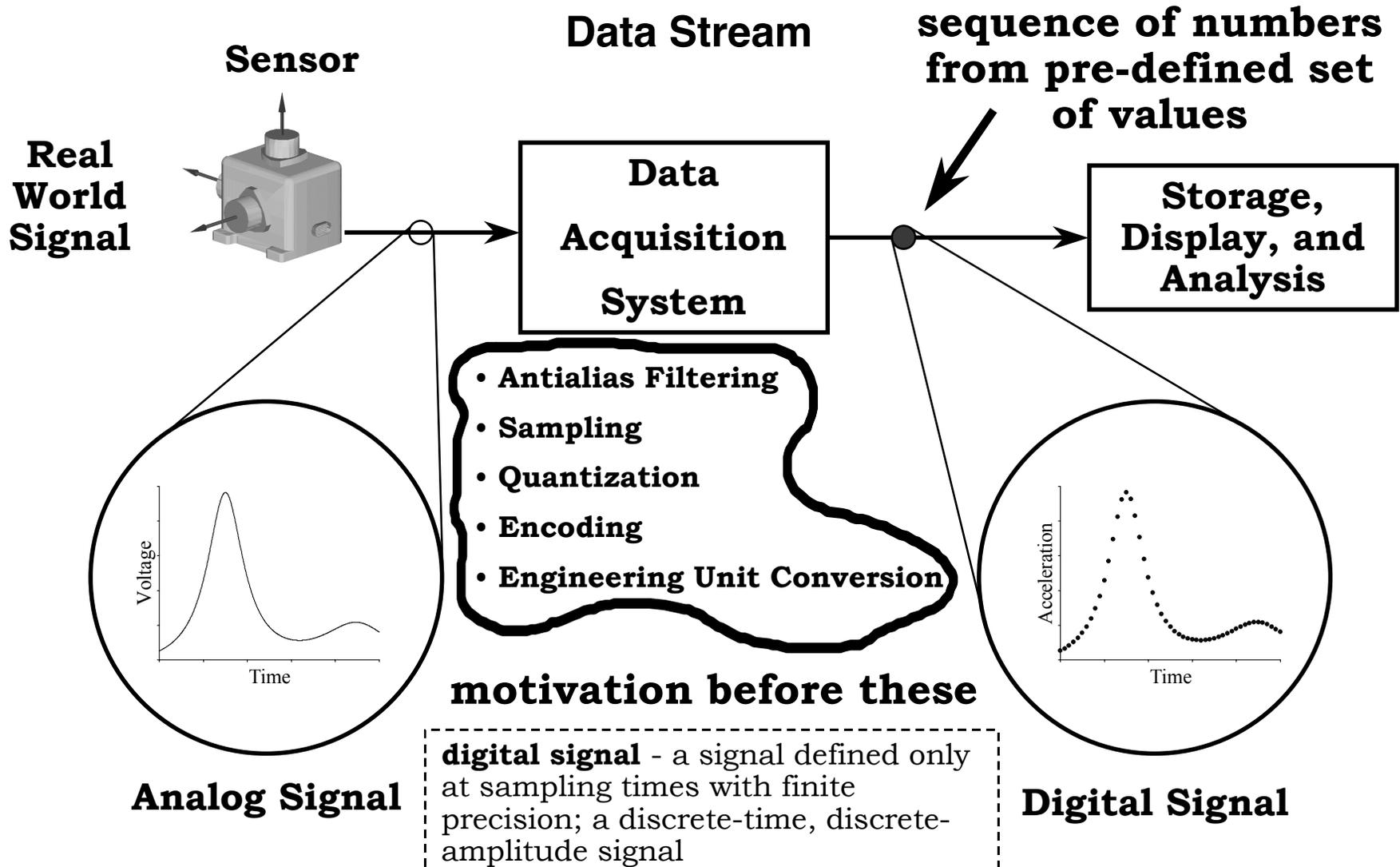
2. Motivation for Analog-to-Digital Conversion

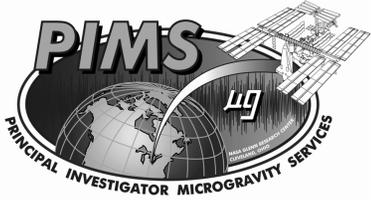
3. Basic Concepts

- processing depends on and impacts the Principal Investigator

4. Tradeoffs and Summary

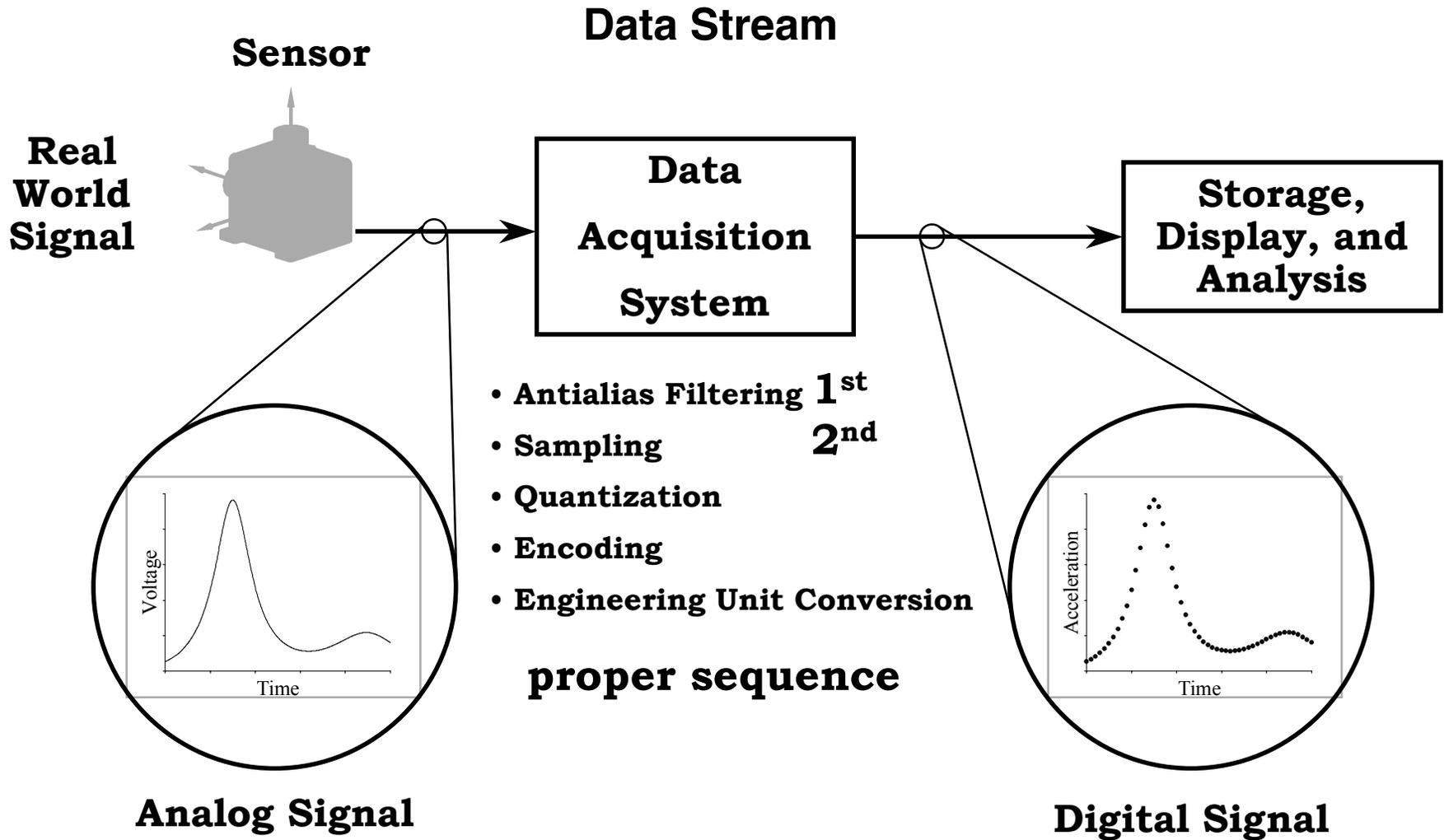






Motivation for Analog-to-Digital Conversion

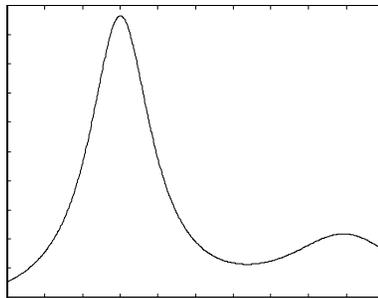
- **Computers**
 - Flexibility. Software does the digital signal processing.
 - Take advantage of the full depth and breadth of processing tools available for this platform.
 - Processing performance does not vary with temperature or time.
- **Reproducibility**
 - No degradation when copying signal.
- **Other factors**



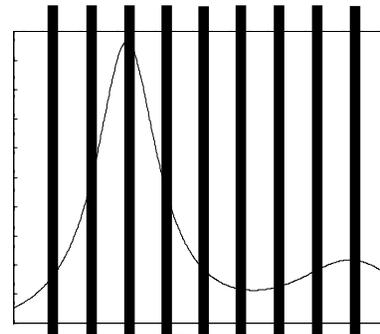
Sampling

has critical implications regarding the information our measurements contain

Analog Signal



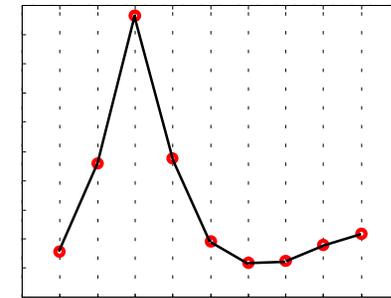
Time



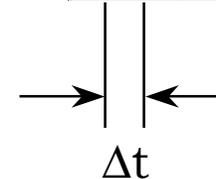
Time

discretization

**connect
the dots**



Time



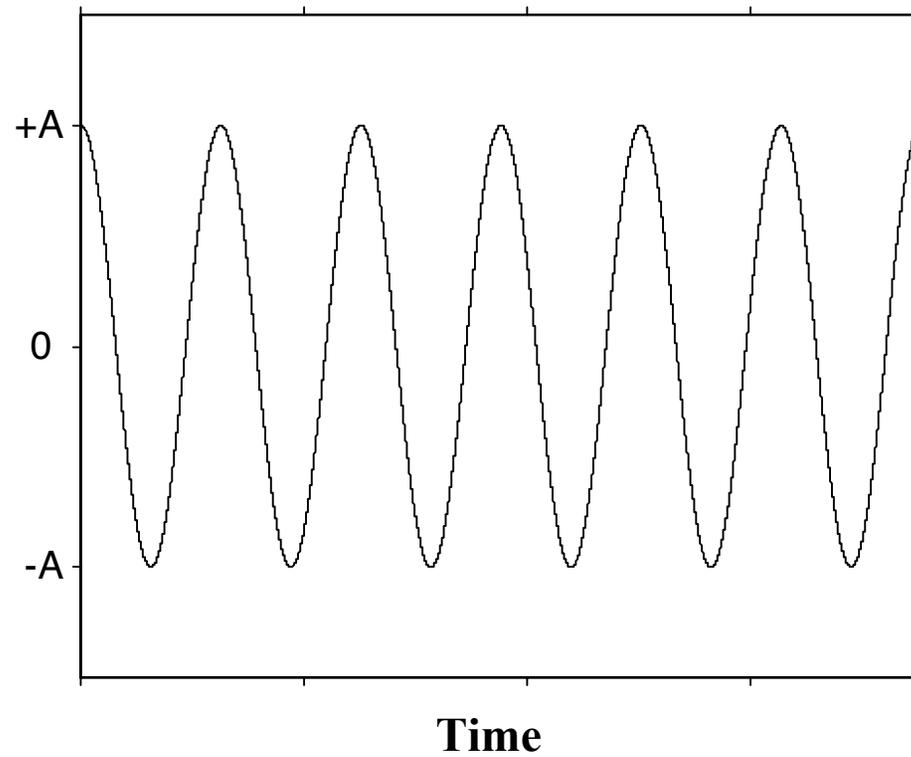
Δt

$$f_s = 1/\Delta t$$

sampling - converting an analog signal to a discrete-time, continuous-amplitude signal

sample rate (f_s) - frequency with which analog signal is sampled (samples per second)

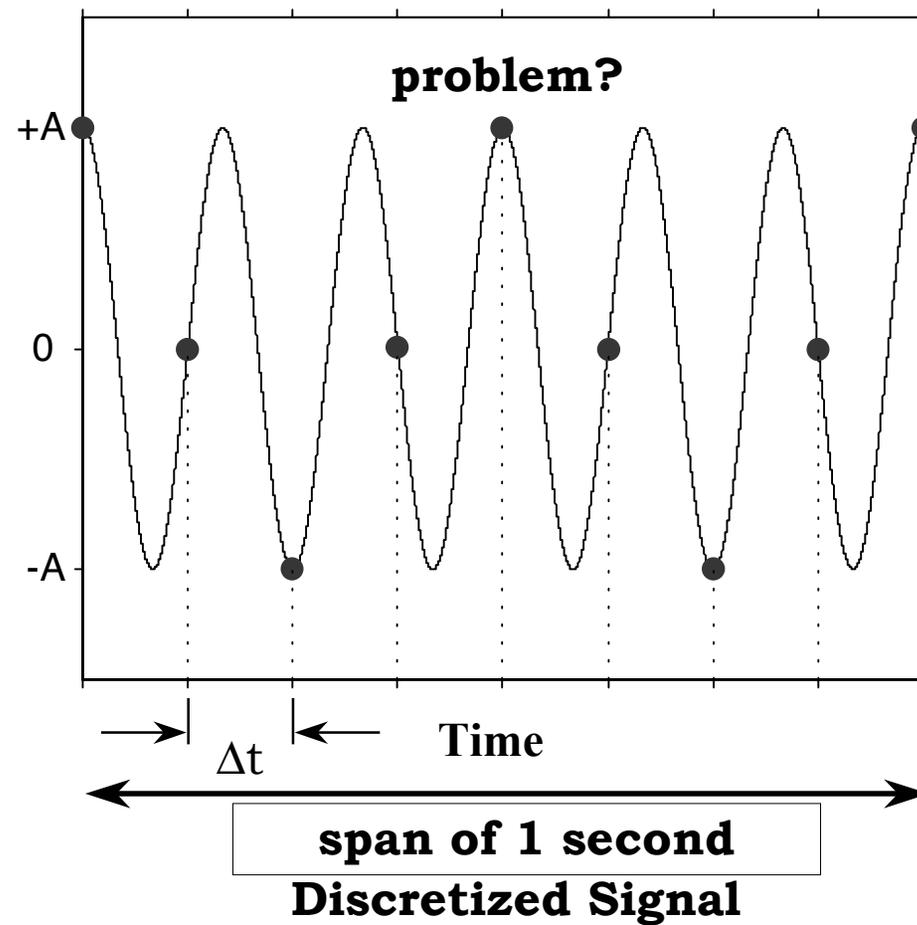
Sampling



**harmless-looking
sinusoid**

Real World (Analog) Signal of Interest

Sampling



sample it

$f_s = 8$
samples/sec

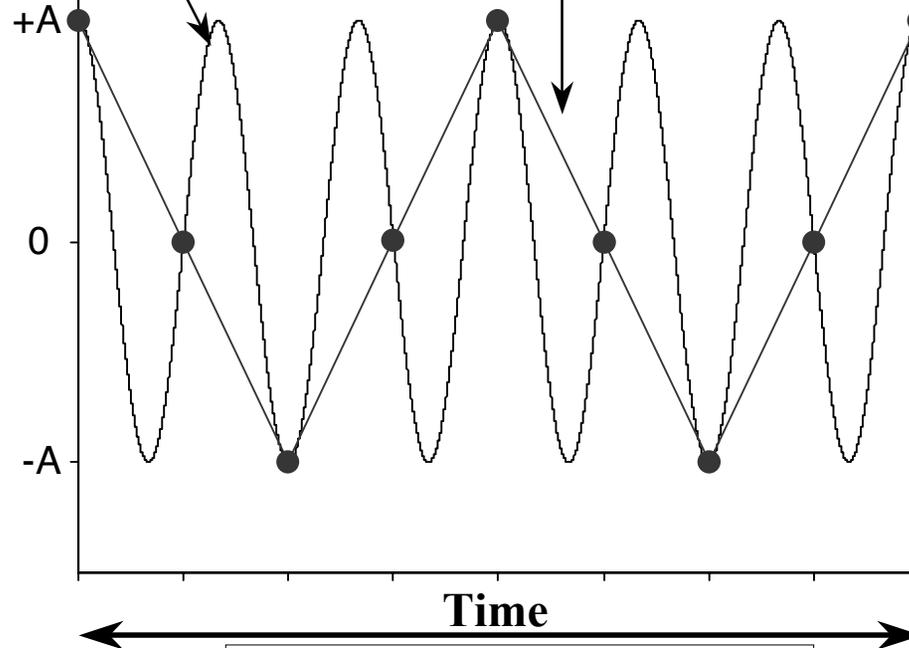
Sampling

6 cycles/sec.

Analog Signal

2 cycles/sec.

Alias



How do we enforce this if we are taking measurements of real world signals and do not know the exact nature of their content or behavior?

How do we avoid aliasing?

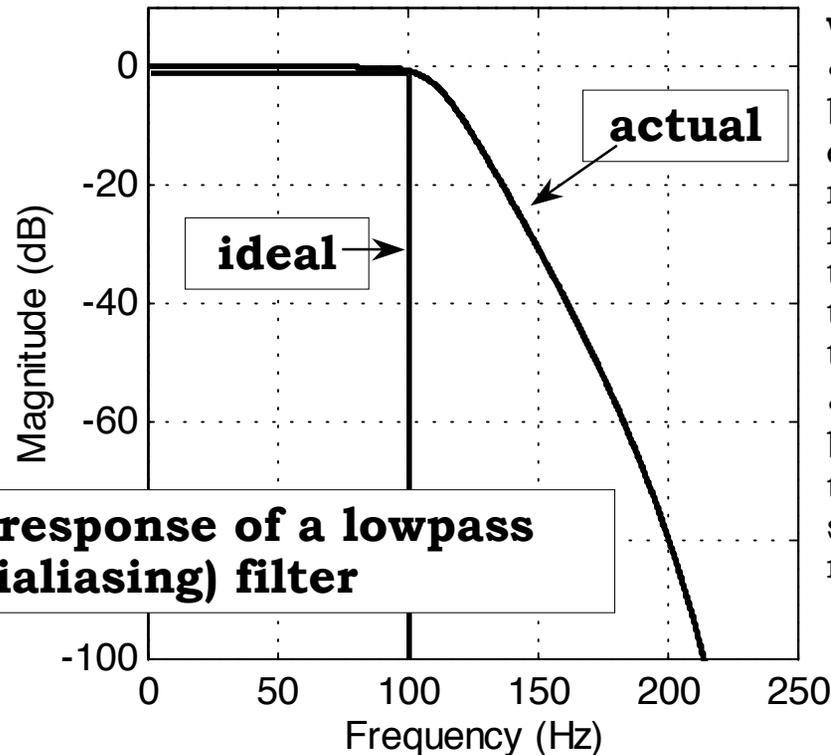
aliasing - high frequency signals manifested as low frequency signals

Nyquist criteria - sample rate at least twice highest frequency contained in the signal of interest

Antialias Filtering

pass without attenuation or amplification below cutoff frequency

total attenuation above cutoff frequency



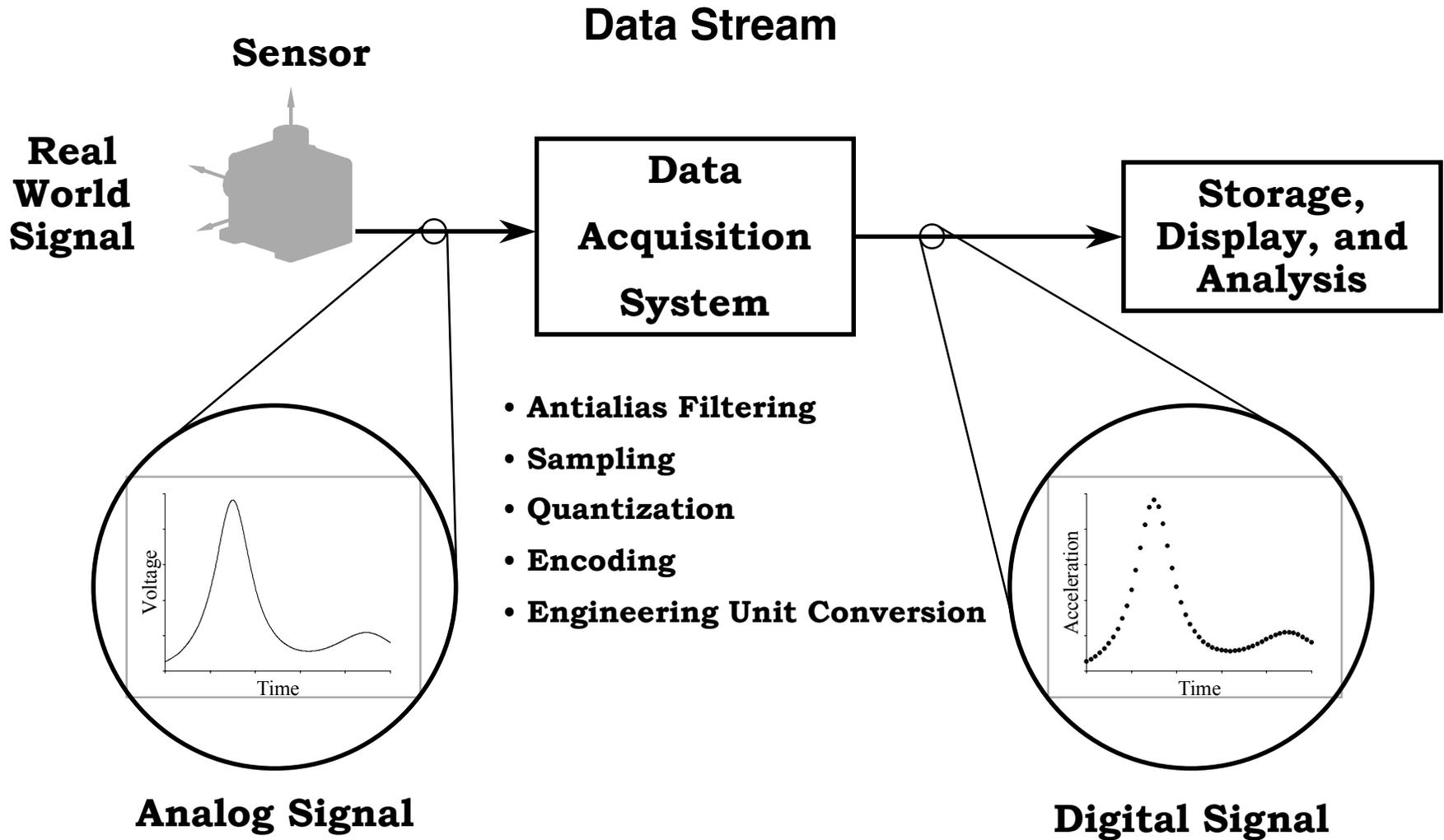
Frequency response of a lowpass (antialiasing) filter

Why does cutoff, f_c , matter?

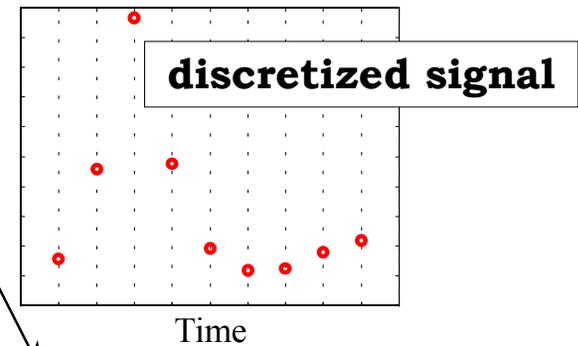
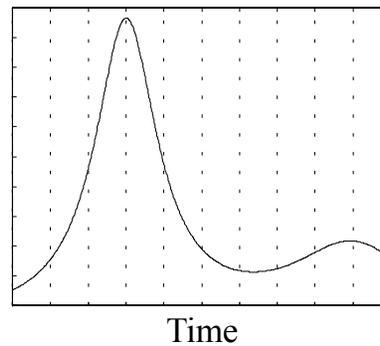
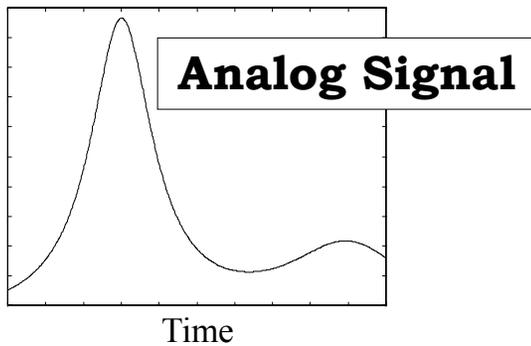
- For acceleration data, besides sensor location, the cutoff frequency (f_c) is one of most important decisions you make. It should be greater than the highest frequency that is of interest or concern to you.
- Higher f_c means higher f_s , but limitations on the transmission bandwidth, storage, and processing resources put a limit on f_s .

antialias filtering - lowpass (bandlimit) analog signal to reduce effects of aliasing

cutoff frequency (f_c) - highest frequency of interest



Quantization



digitization

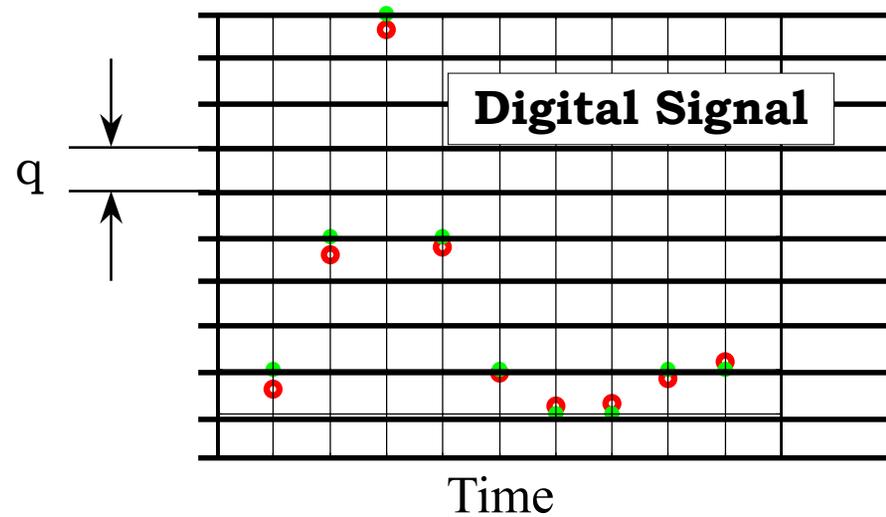
quantization - conversion of discrete-time, continuous-amplitude signal to discrete-time, discrete-amplitude signal

$$q = V_{fs} / (2^b - 1)$$

$b = \# \text{ of bits}$

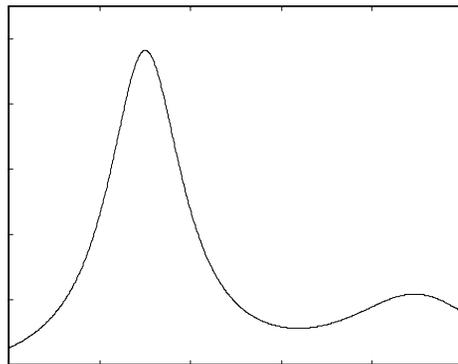
$V_{fs} = \text{full scale voltage}$

$q = \text{quantization level}$



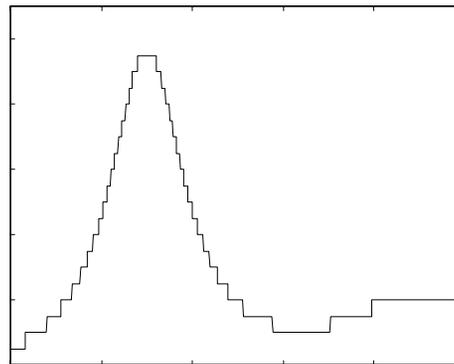
Quantization

**Analog
Signal**



Time

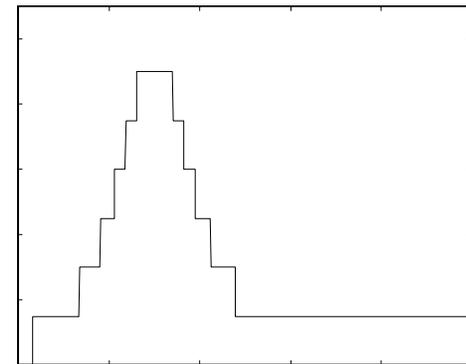
**“Noticeable”
Quantization
Error**



Time

some imprecision

**“Significant”
Quantization
Error**

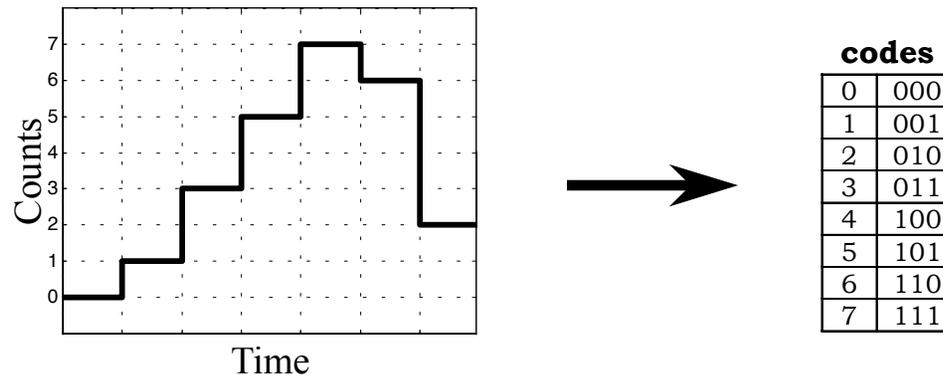


Time

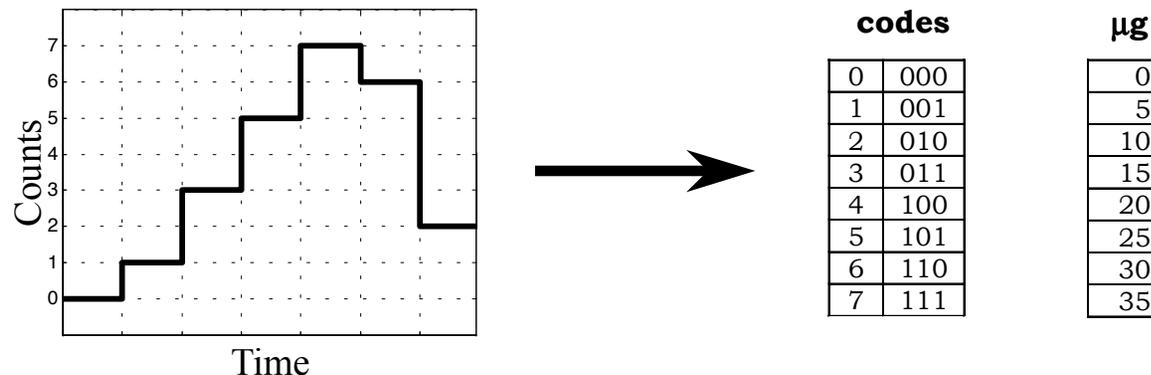
even more imprecision

Encoding & Engineering Unit Conversion

- **Encoding** - assigning unique codes to the quantized samples



- **Engineering Unit Conversion** - translation of encoded values to desired “final” representation





Tradeoffs and Summary

Analog-to-Digital Conversion - computer processing is the motivation

1. Antialias Filtering

- lowpass filter → leads to loss of high frequency information

2. Sampling

- sample rate ← transmission, storage, and processing
- discretization in time → aliasing

3. Quantization

- digitization of amplitude → precision limited by number of bits

4. Encoding

5. Engineering Unit Conversion